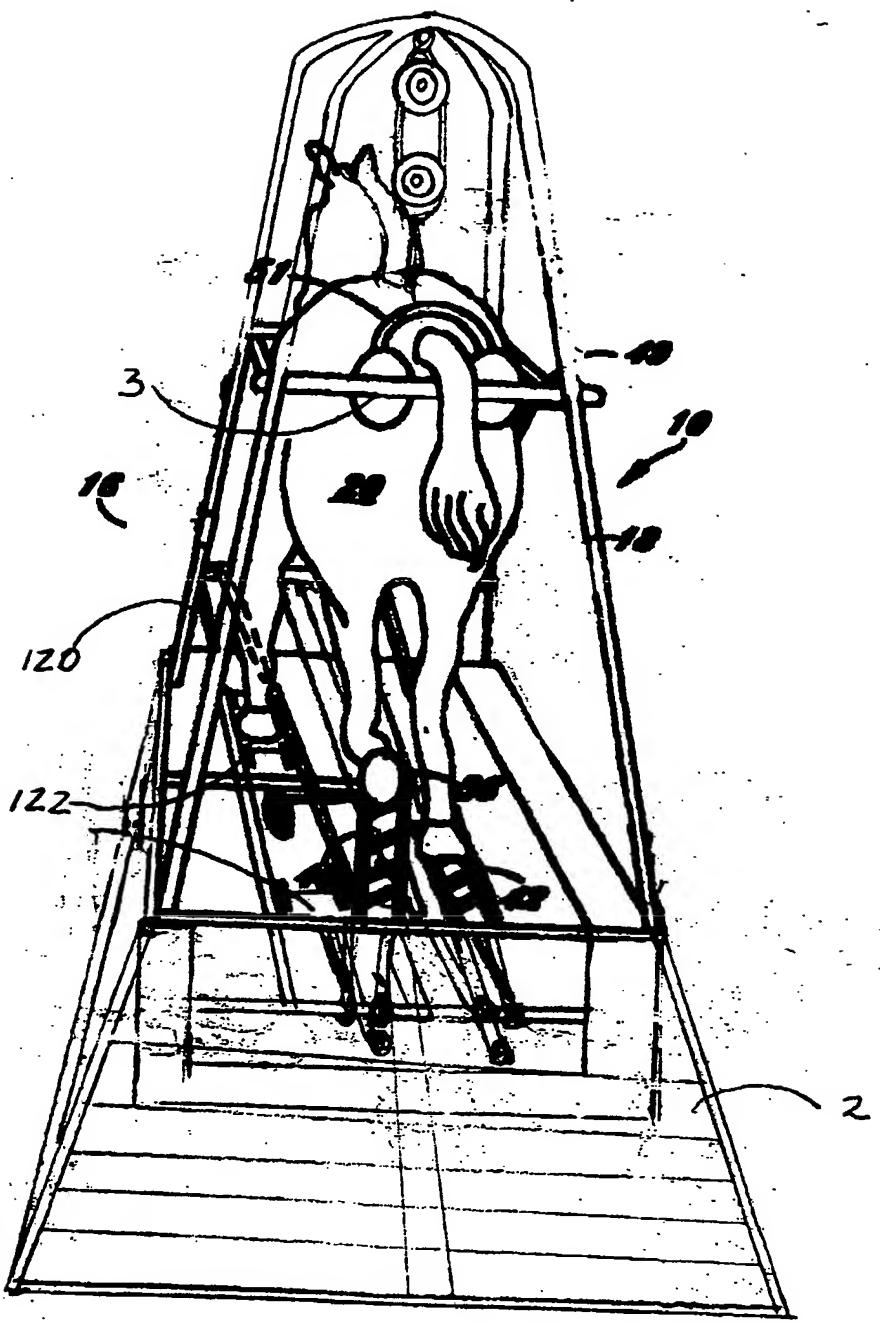


*Fig. 1*



*Fig. 2*

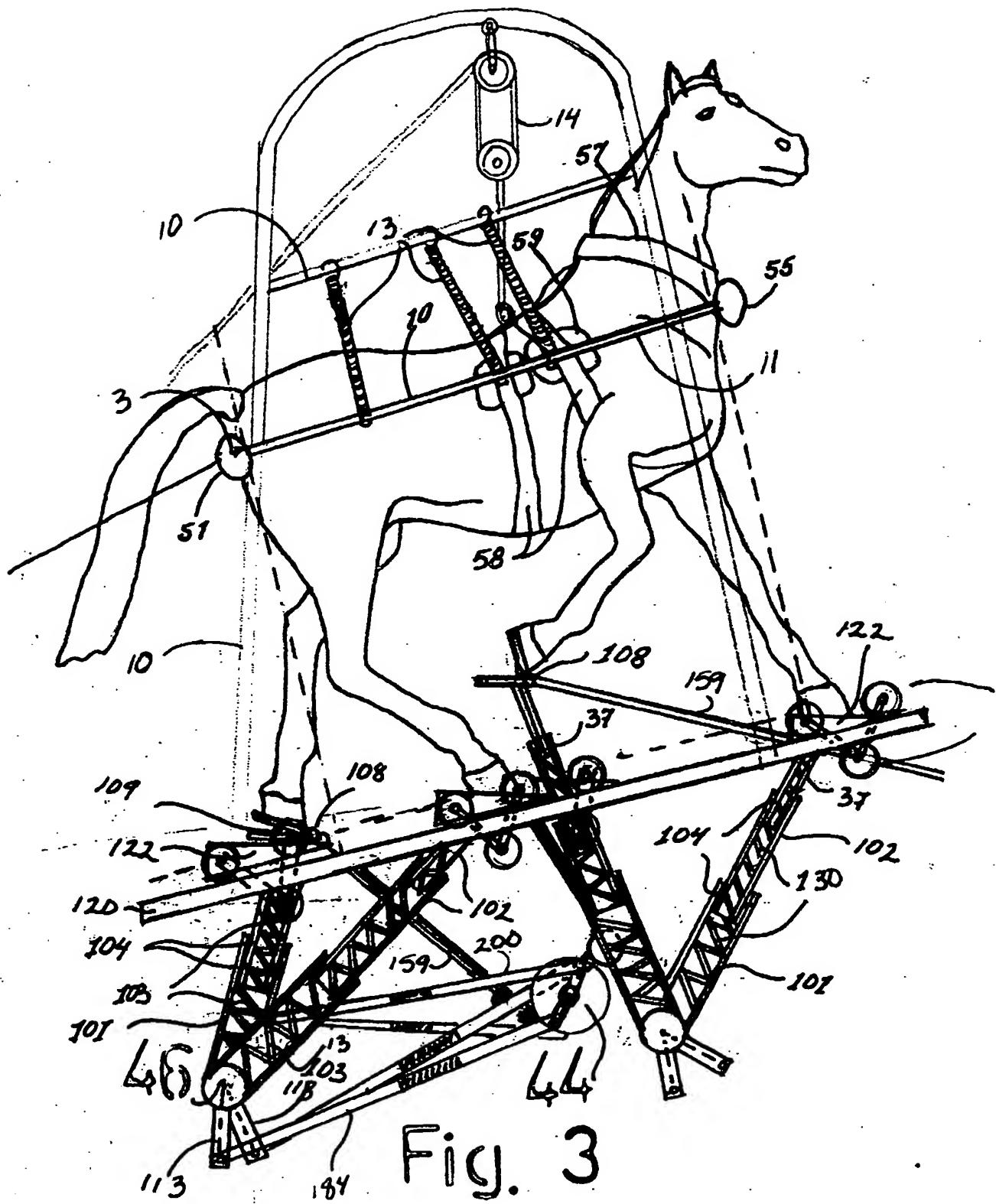


Fig. 3

Fig. 4

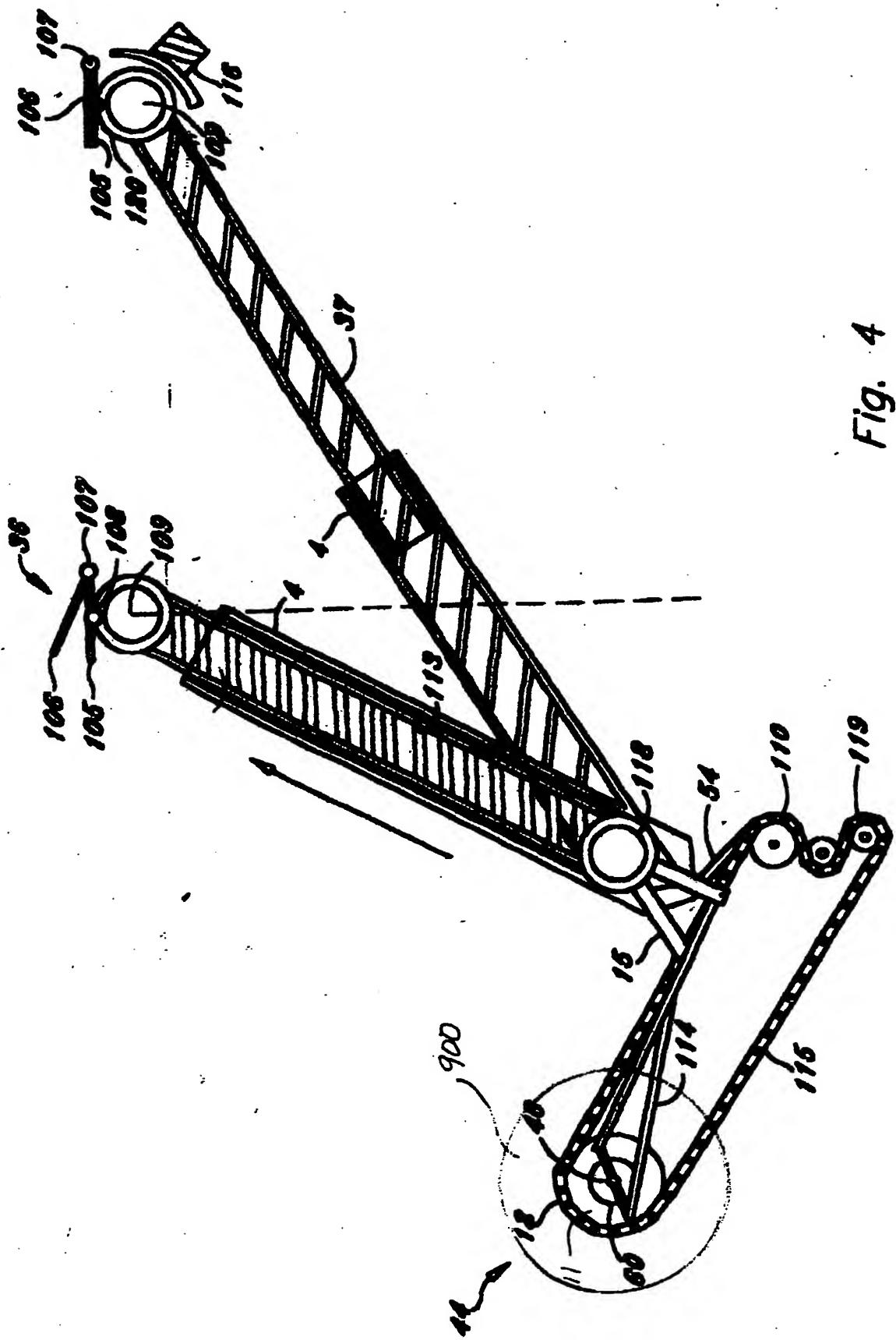
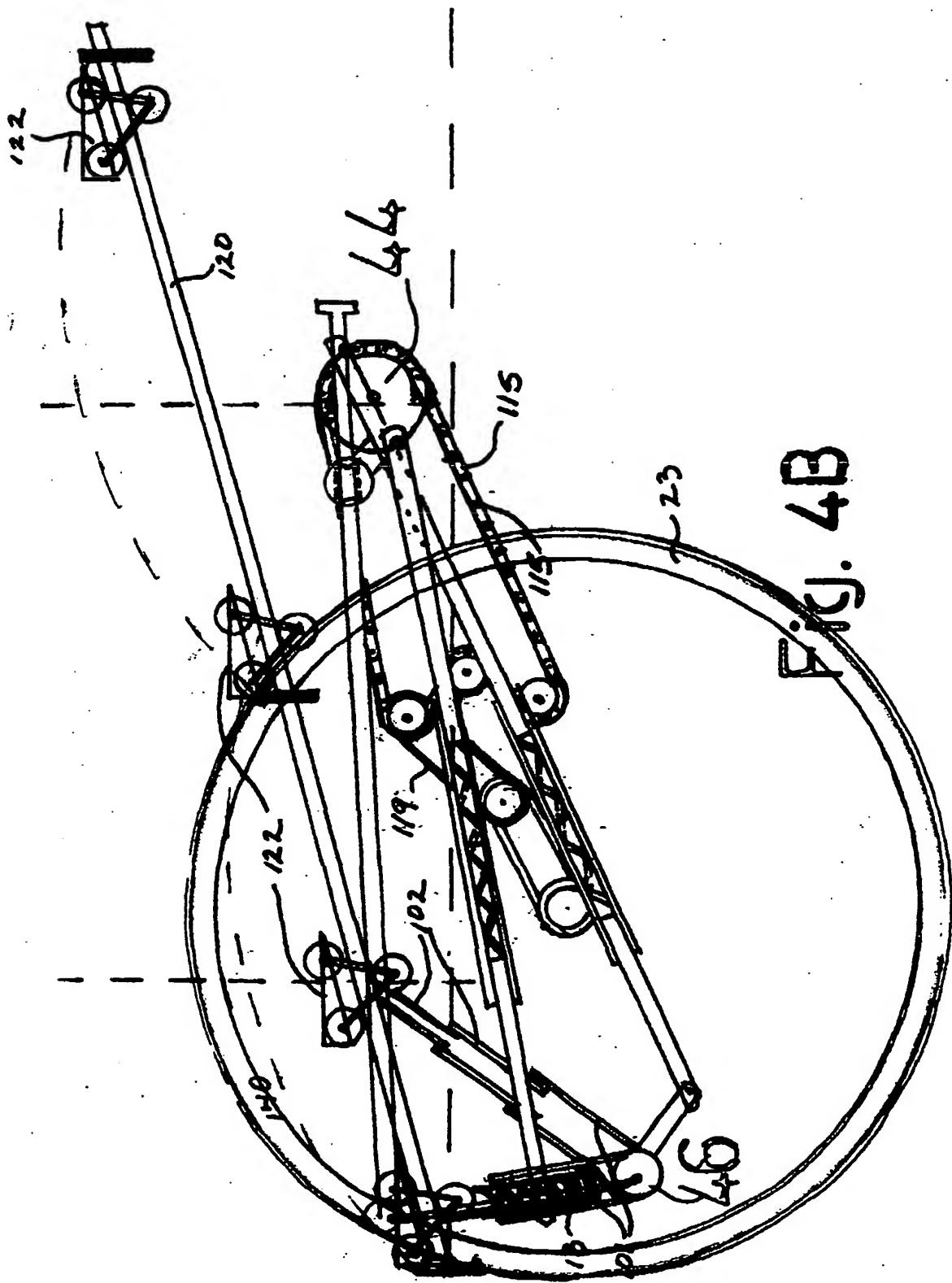


Fig. 4B



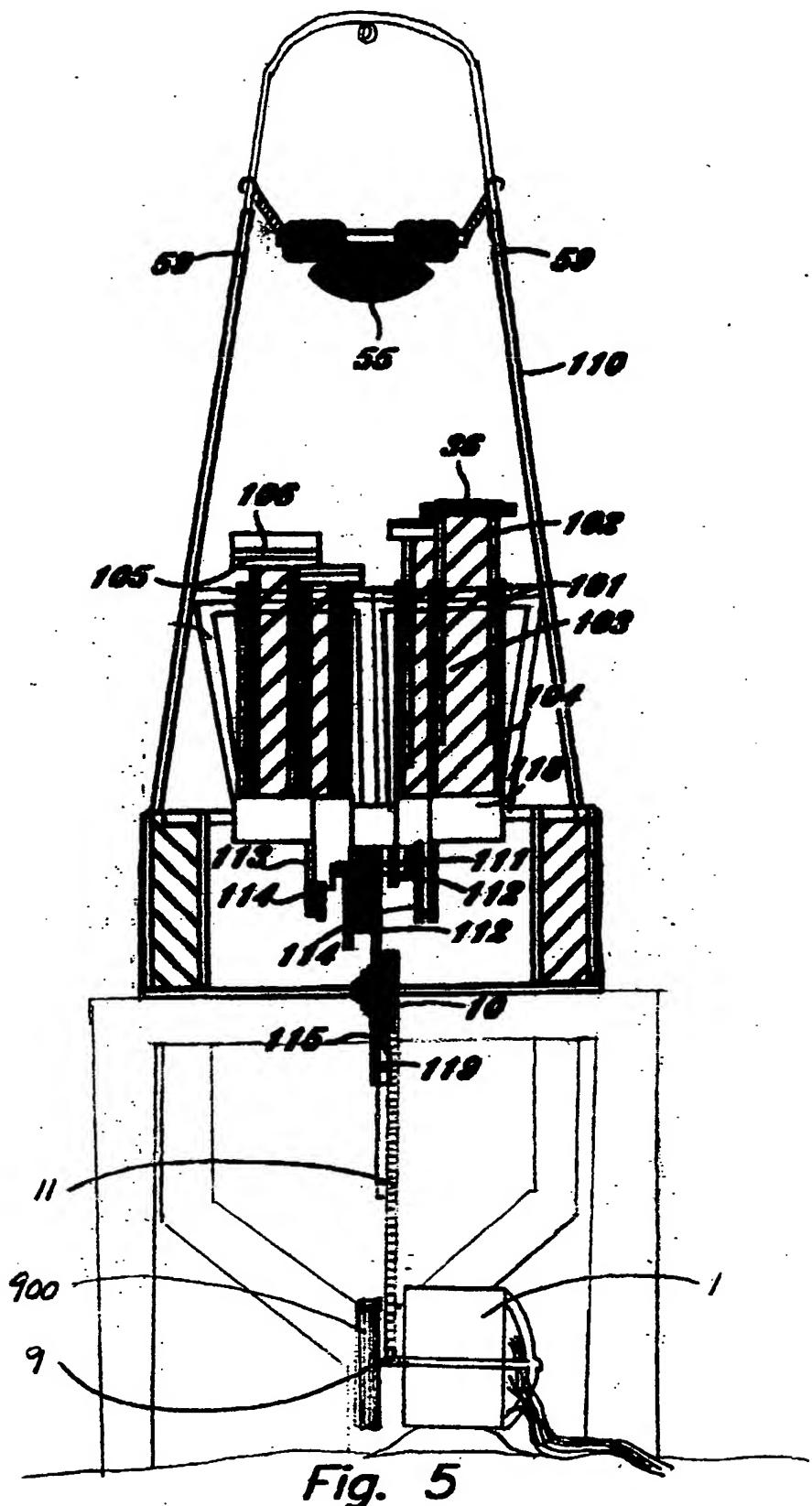
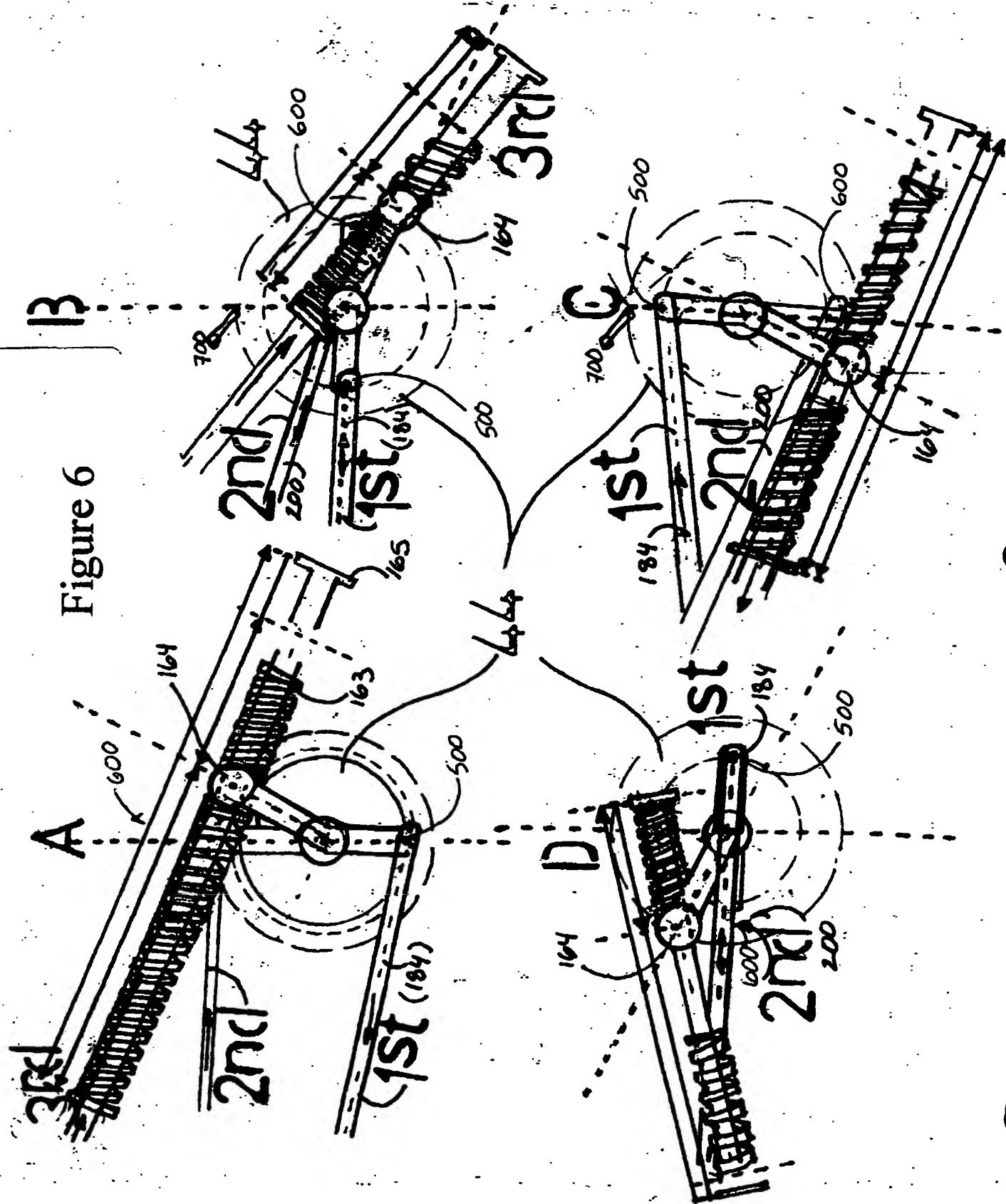


Fig. 5

B

Figure 6



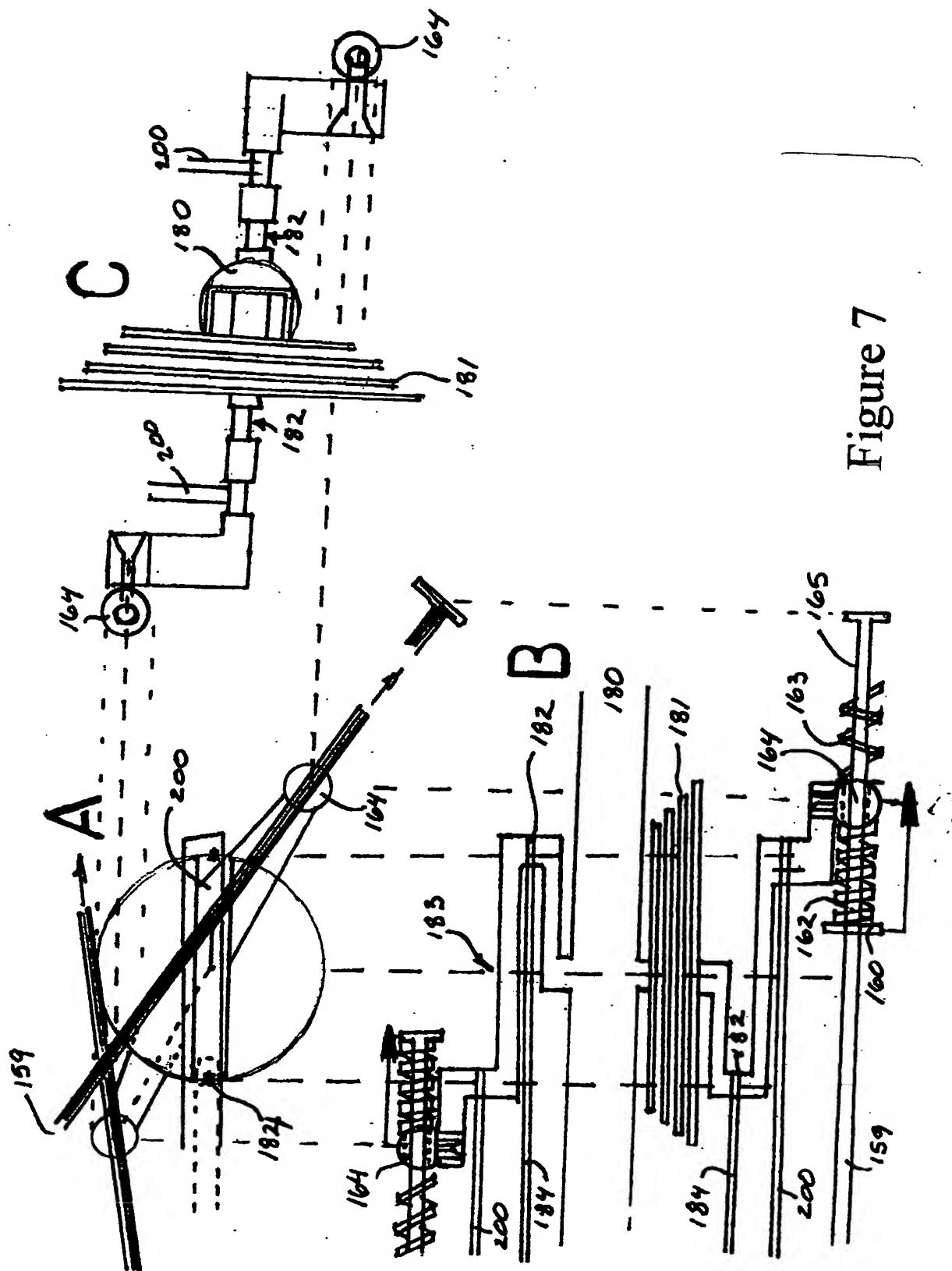


Figure 7



Fig. 8A

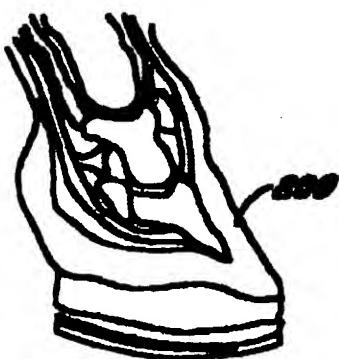


Fig. 8B

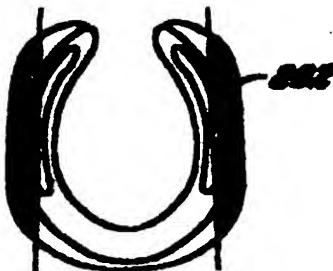


Fig. 8C

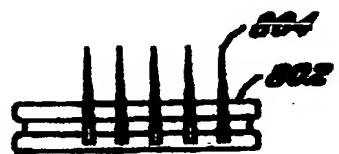


Fig. 8D

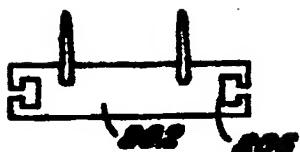


Fig. 8E



Fig. 8F



Fig. 8G

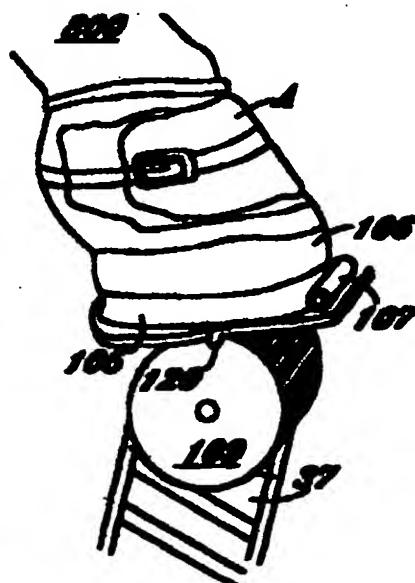


Fig. 8H

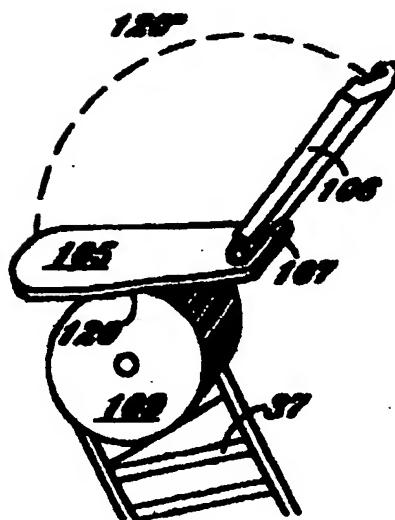
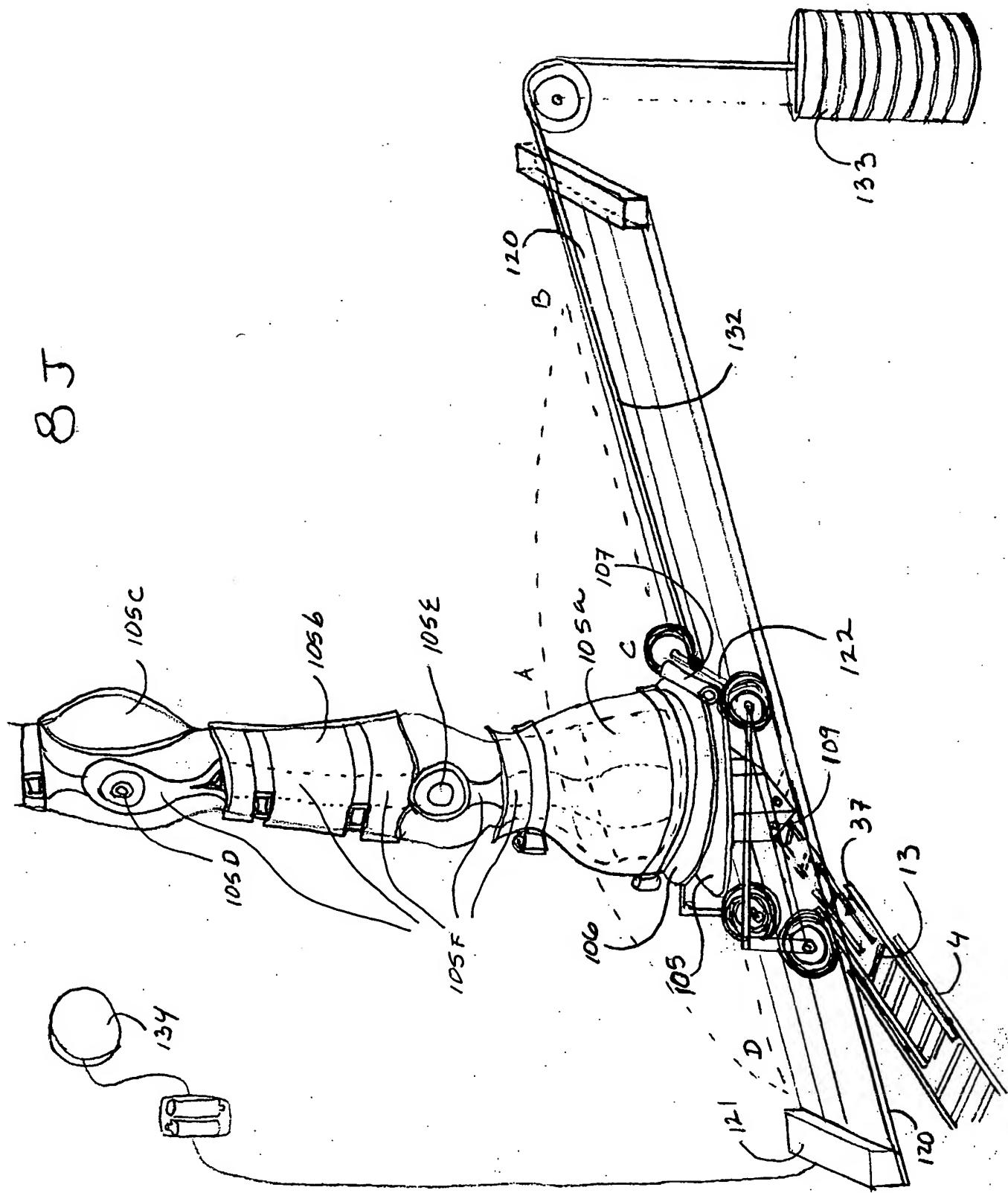
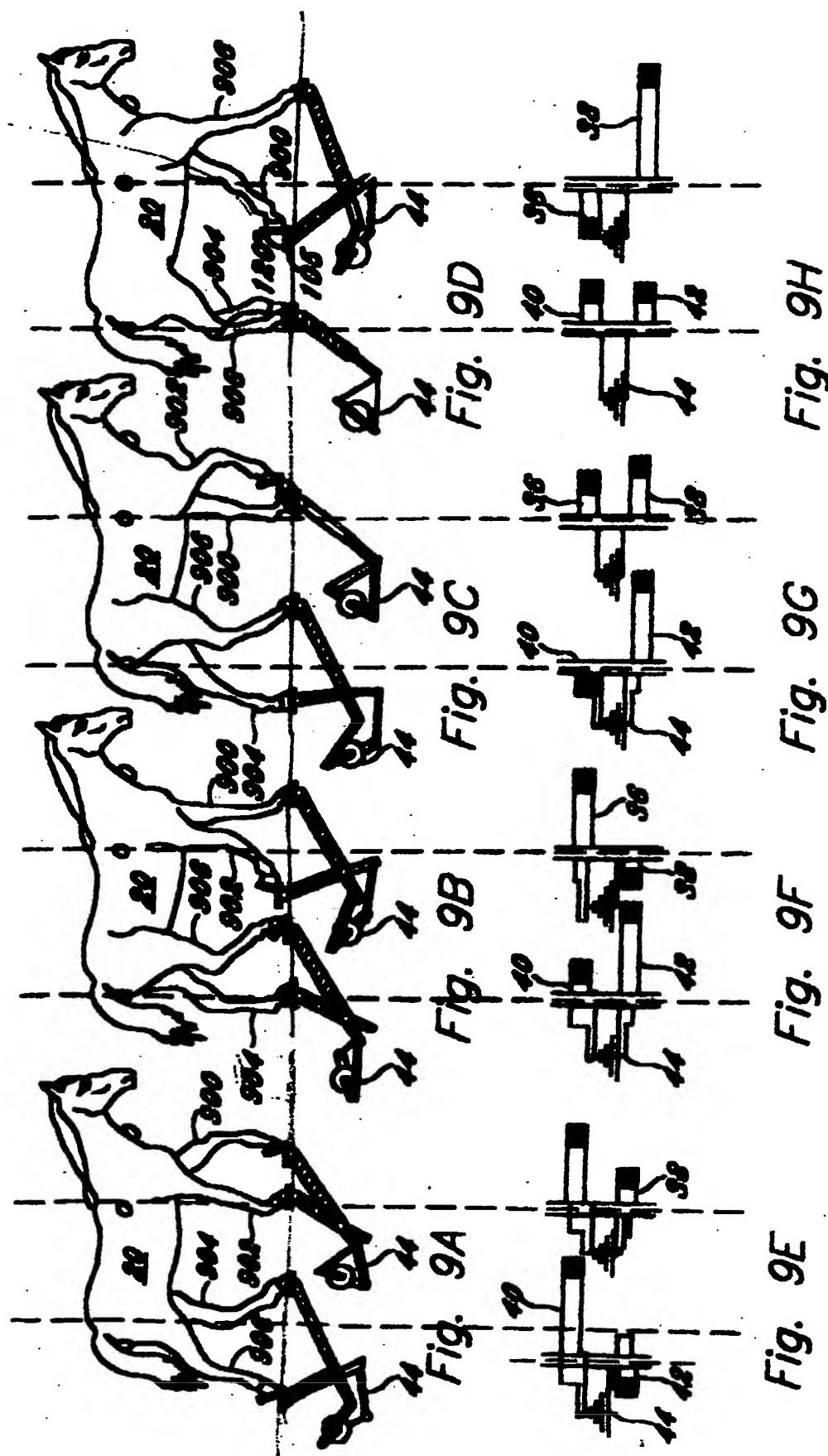


Fig. 8I

8 JT





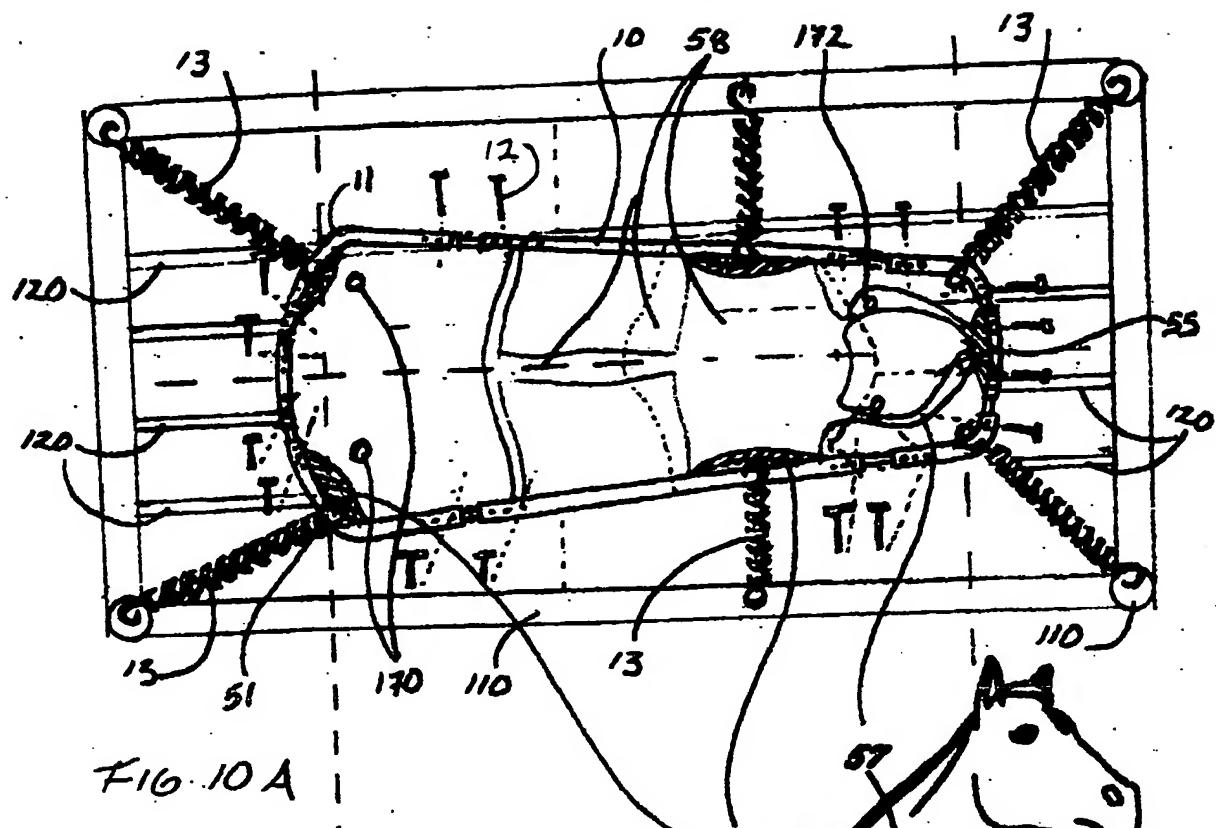


FIG. 10A

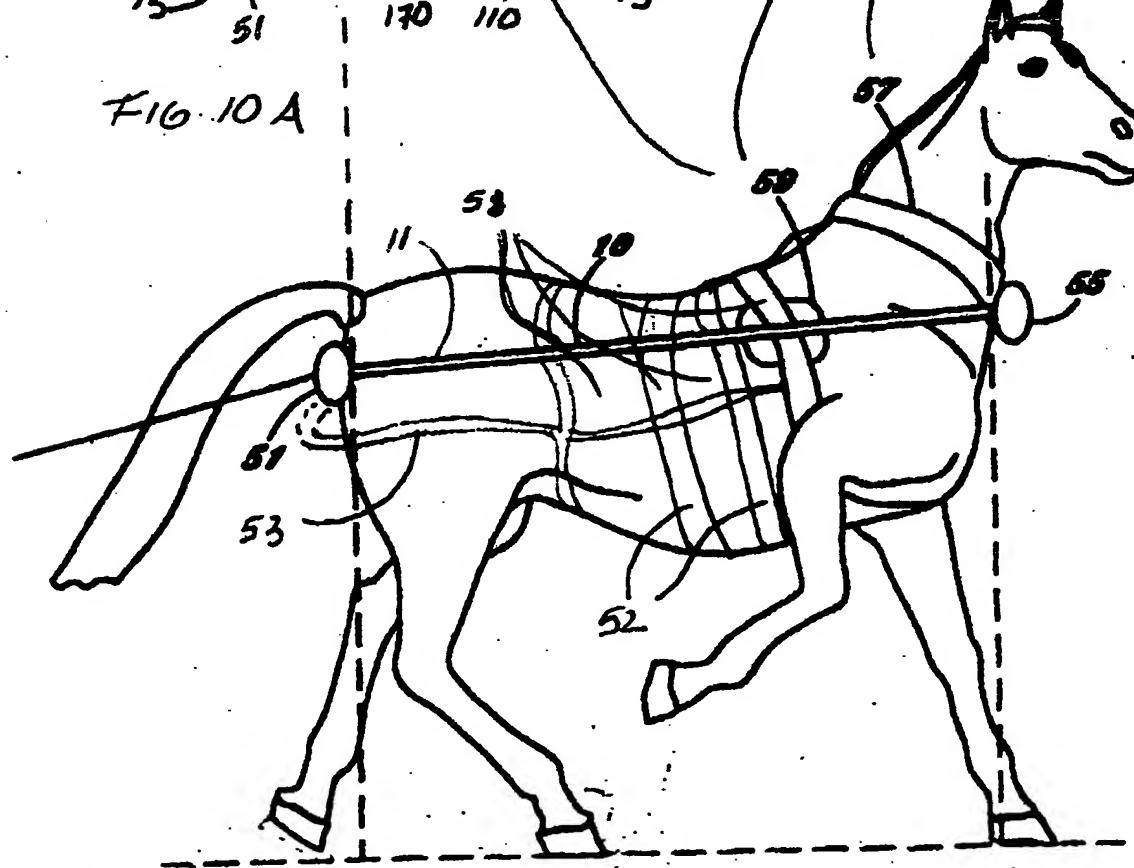


Fig. 10B

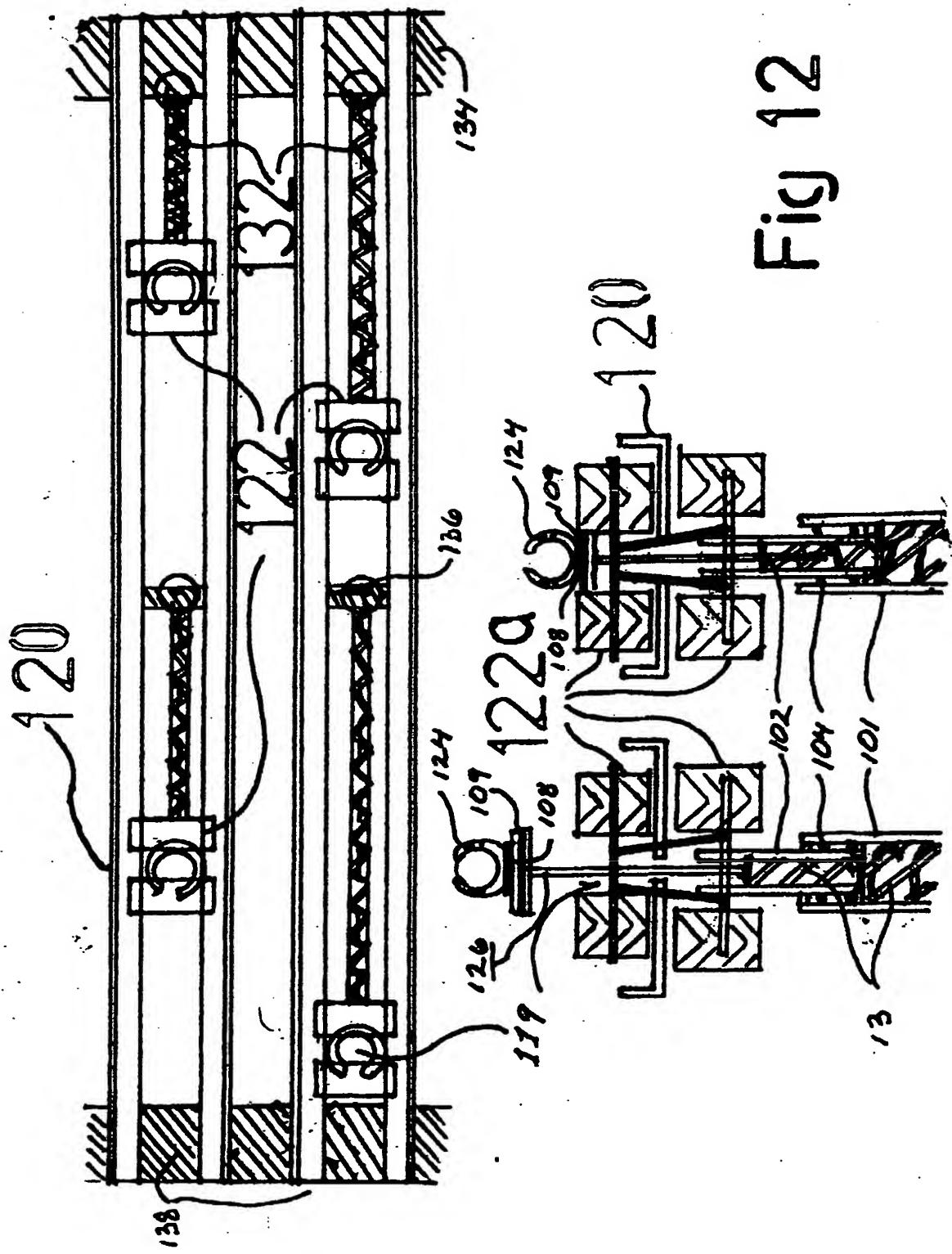
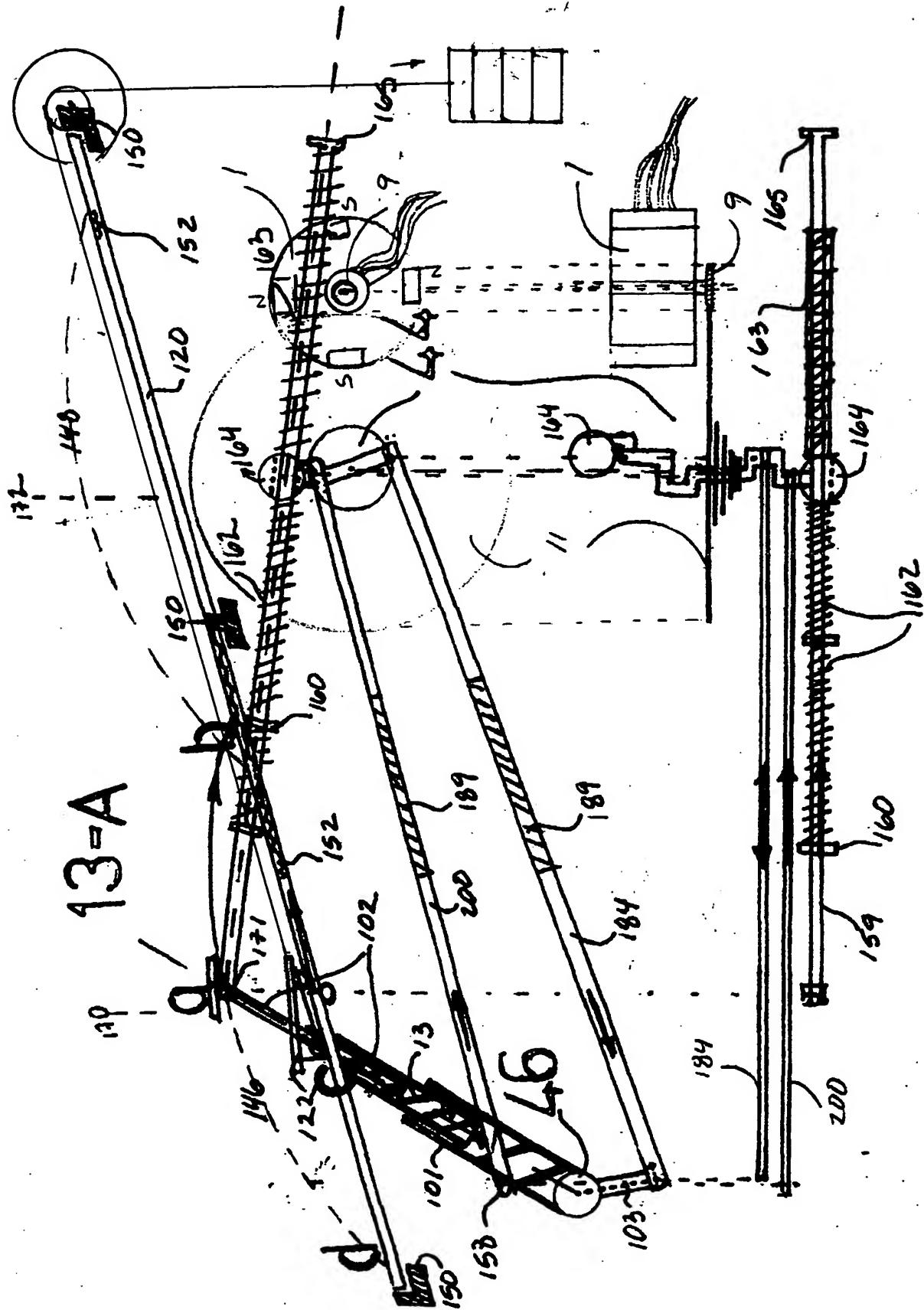
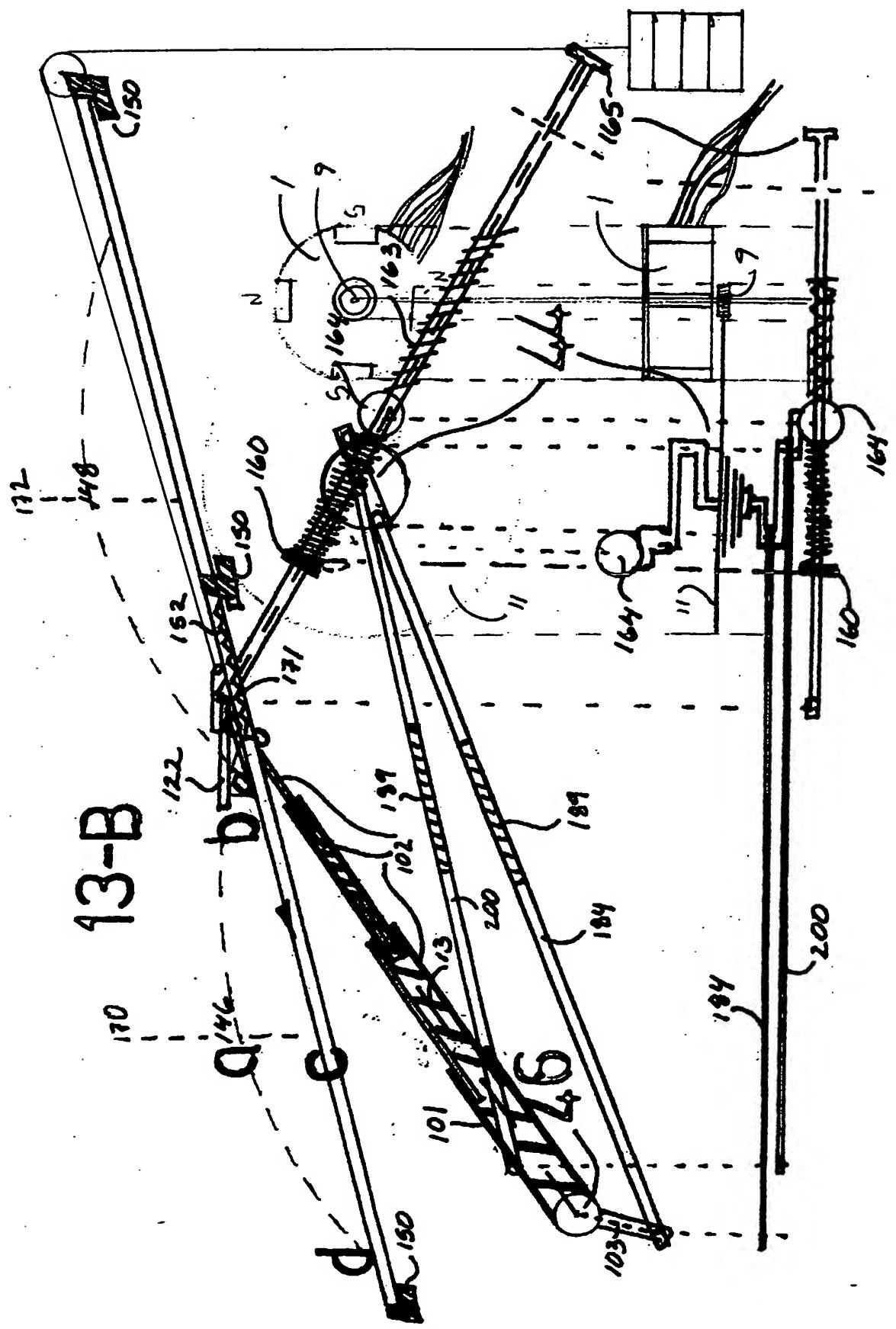
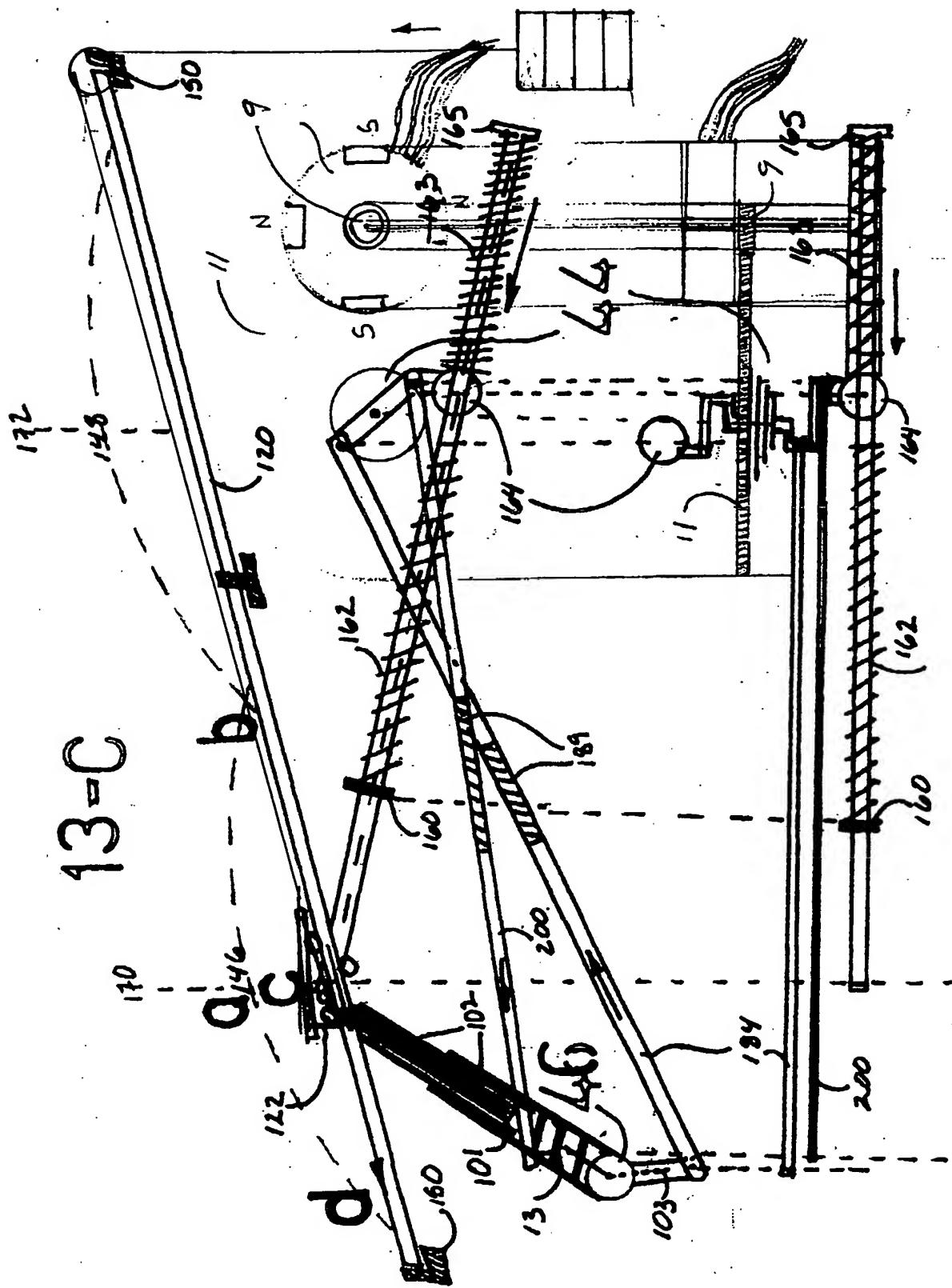


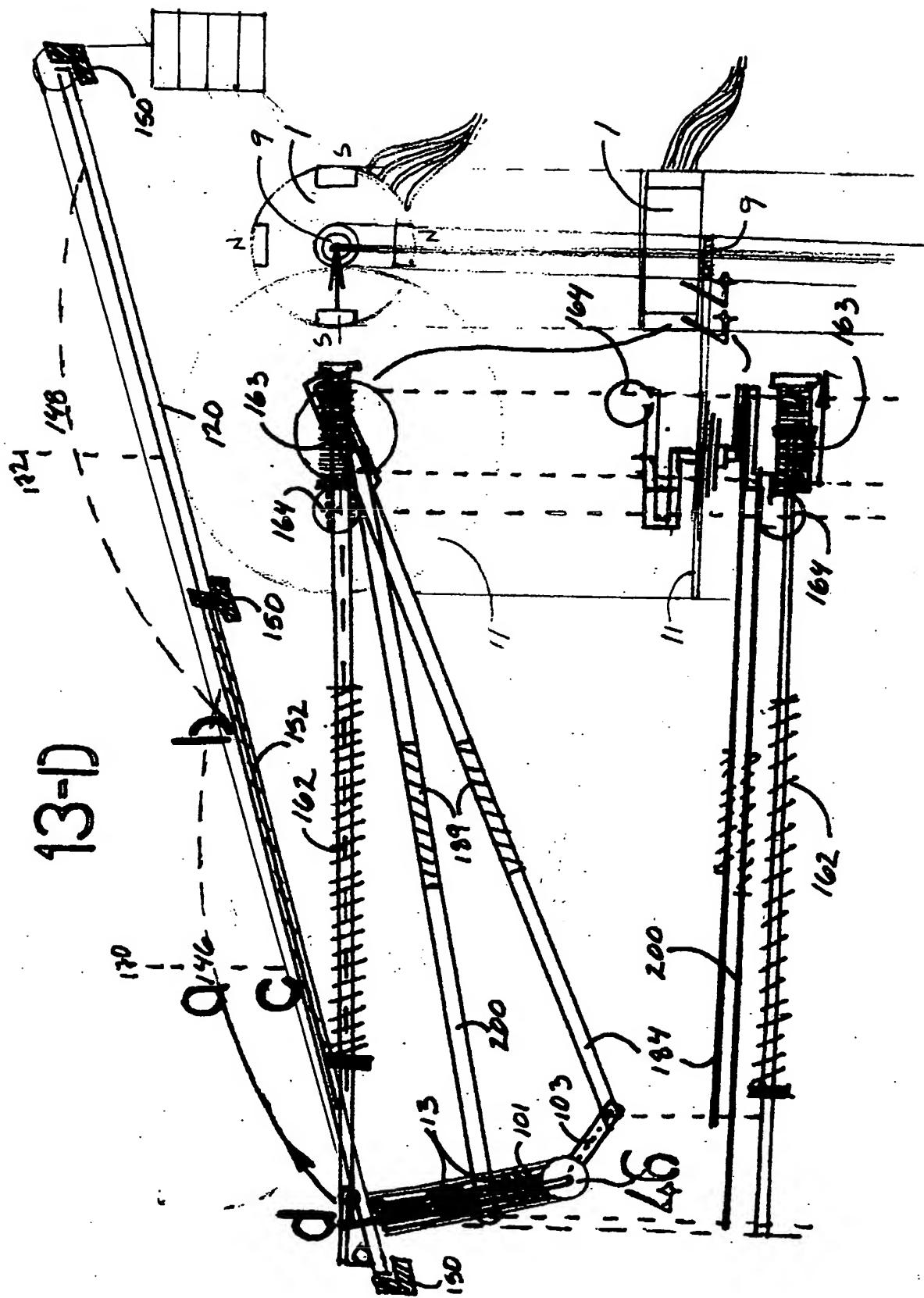
Fig 12



13-B









- 200 Providing a frame composed by and an upward adjustable slope that is supported by the ground.
- 202 coupling at least two foot link to at least one electricity generator alternator or similar electronic device in order to produce electricity for its further distribution or storage.
- 204 providing at least four foot supports, wherein at least one foot support is in direct communication with the foot link
- 206 providing a coupling system in rotational communication with at least one foot link to translate the parabolic stepping motion of an animal into 360 degrees rotational momentum.

Figure 11